

ELEC 3300

Introduction to Embedded Systems

Topic 7

Timer and Counter

Prof. VINOD Prasad

Course Overview

Assembler

Instruction Set Architecture

Memory

I/O System

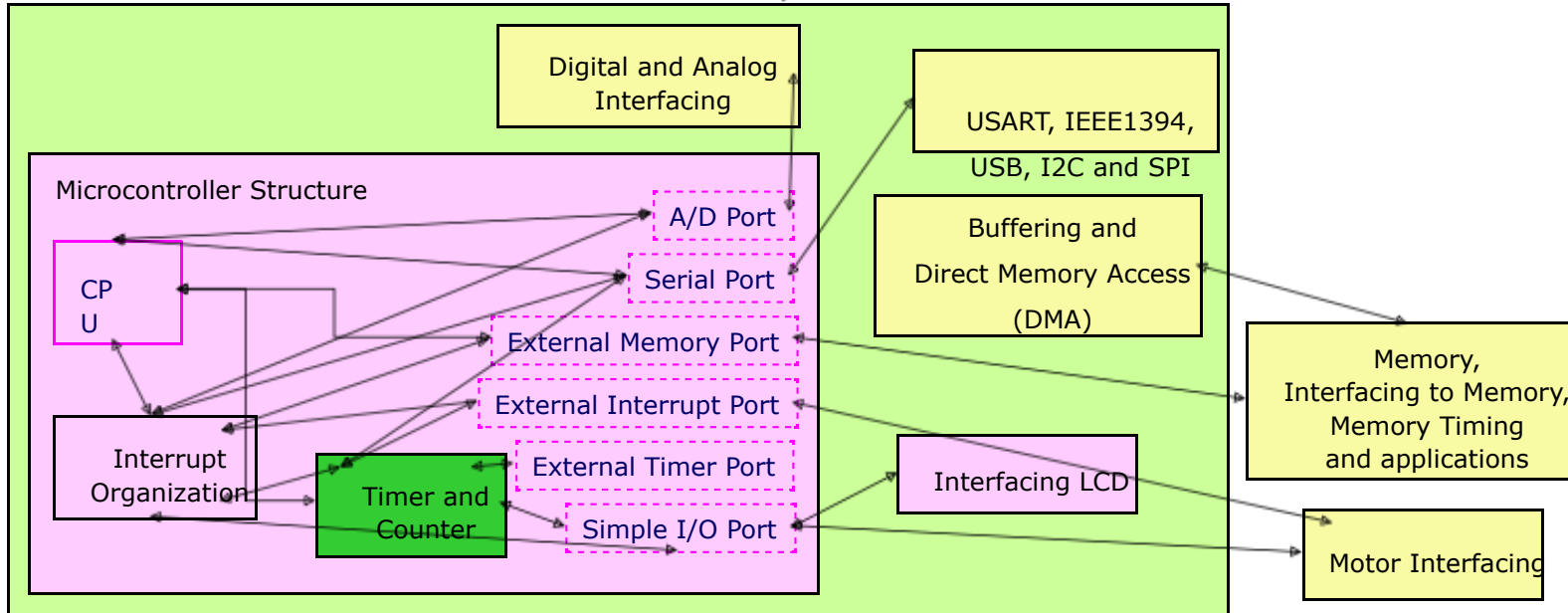
Datapath & Control

Introduction to
Embedded Systems

More about
Embedded Systems

Basic Computer
Structure

MCU Main Board



In this course, STM32 is used as a driving vehicle for delivering the concepts.

To be covered

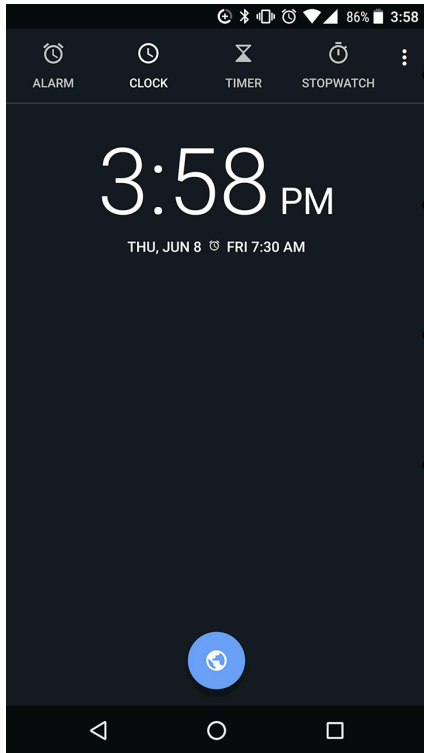
In progress

Done

Expected Outcomes

- On successful completion of this topic, you will be able to
 - Summarize the importance of the timer in microprocessor
 - Distinguish the features of timer and counter
 - Demonstrate some applications of timers
 - Understand the timing diagram of the general-purpose timers in STM32.

Why TIMERS?



CLOCK – display real time in multiple time zones

ALARM – alarm at certain (later) time(s)

STOPWATCH – measure elapsed time of an event

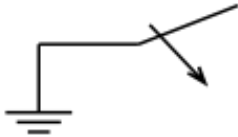
TIMER – count down time and notify when count becomes zero (introduce a delay, count an event)

Timer-mode and counter-mode operation

- Two modes of operation: TIMER and COUNTER modes**

Start as timer:

Switch
press one time



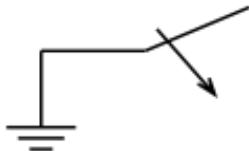
Generates predefined number of pulses
(based on the set time) for each press



Periodic
Waveform

Start as counter:

Switch
press one time

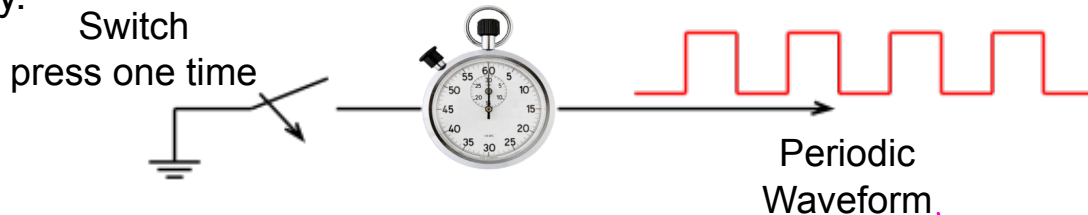


Generates one pulse for each press



Timer-Mode Operation

- An output pulse generated each time the counter reaches zero (or preset value) provides a signal with a software-programmable frequency.

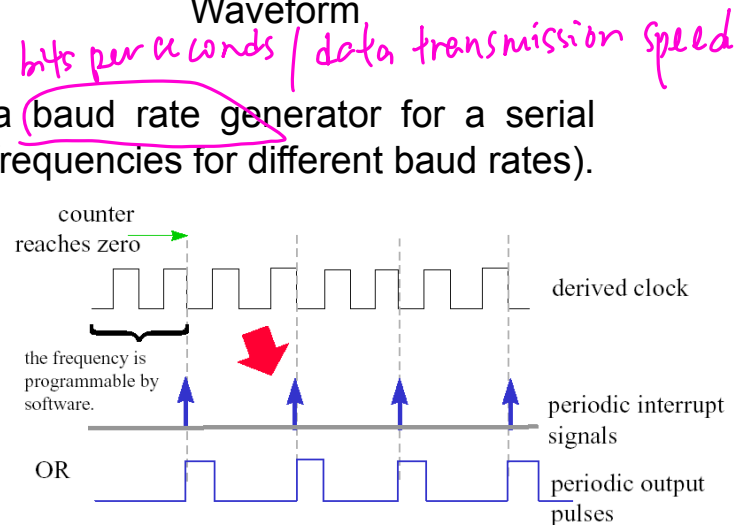


- Applications:

- A common use for this output is as a baud rate generator for a serial communication interface (different CLK frequencies for different baud rates).
- generating waveforms for audible tones.

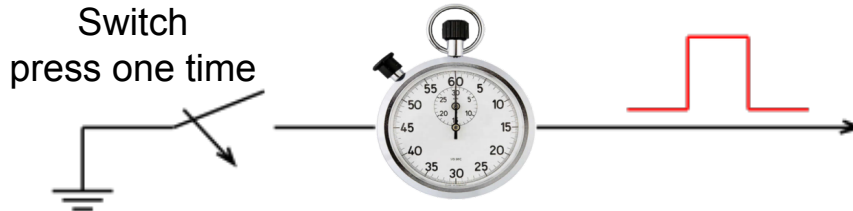
(Try this <https://www.szynalski.com/tone-generator/>)

- Timing the length of event

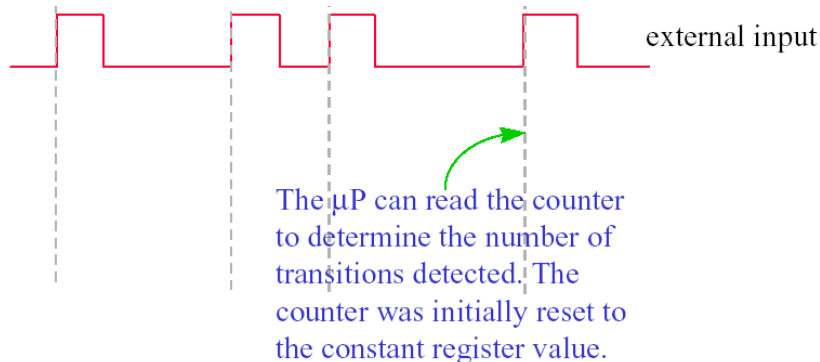


Counter-Mode Operation

- It is useful for interfacing to other devices that produce streams of possibly non-period pulses that must be counted ◦

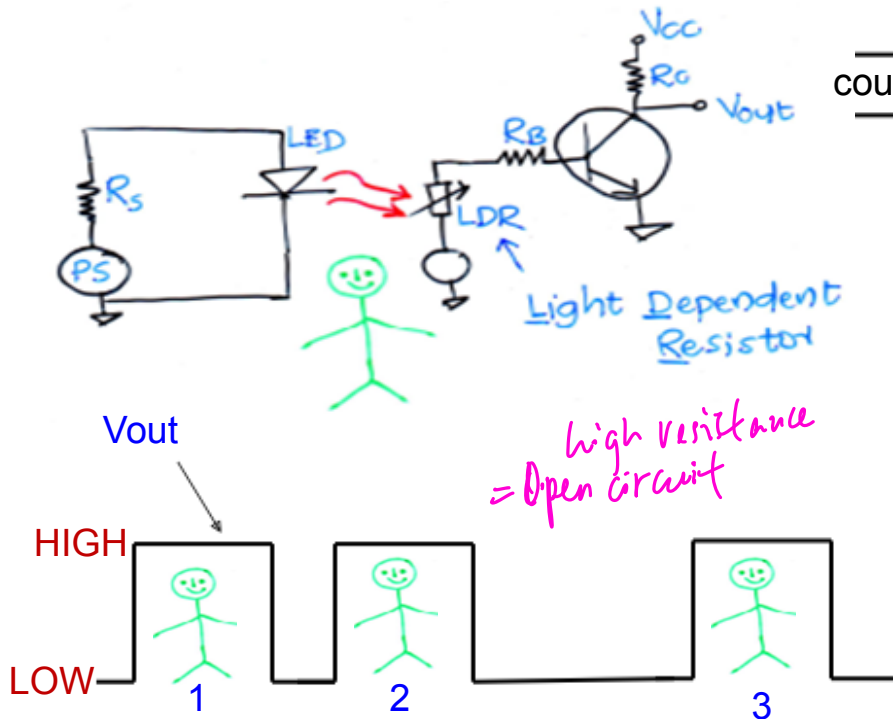


- Applications:
 - Count the number of times that a user has pressed a key.



Real-world Examples of Counter-mode operation

Counting People (customers of 7-11 store)



Condition #1 - No person between LED and LDR:

LDR turns ON while receiving light from LED ☐ sufficient base current ☐ large collector current ☐ transistor ON (saturation) ☐ V_{out} is LOW.

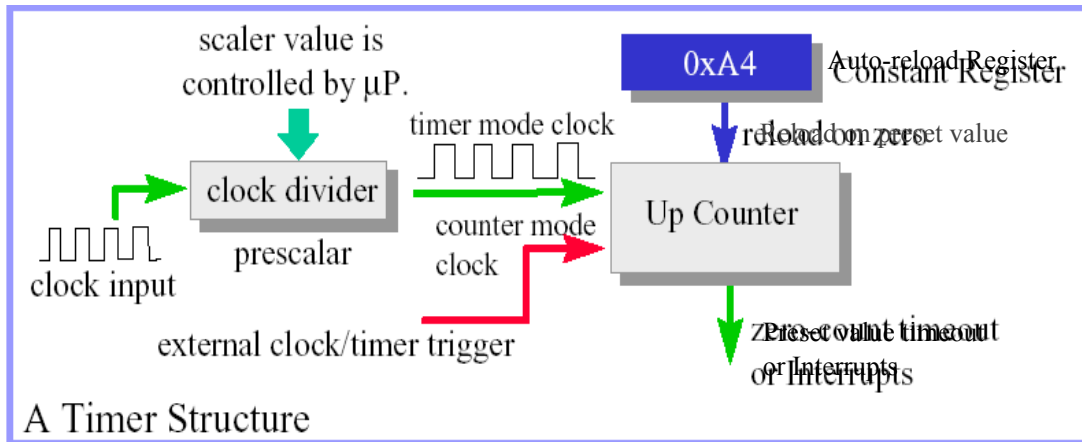
Condition #2 - Person between LED and LDR:

LDR turns OFF as no light from LED ☐ No base current ☐ No collector current ☐ transistor OFF ☐ V_{out} is HIGH.

Counter value = number of pulses = number of people

Timer Structure

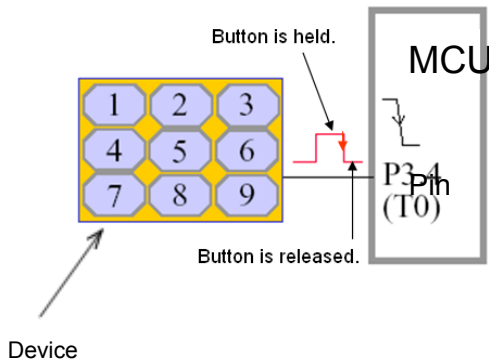
- Devices that use a high speed clock input to provide a series of time or count related events
- Building block of a timer



- Other important registers:
- Counter Register, **Mode Register**, **Control Register**, **Status Register**
Control Register (Timer Control Register) (Implementation)
Status Register (Timer Status Register) (Implementation)
 triggers a followup action like interrupt generation (Implementation)

Example 1 – Event Counting

- Say, you want a microprocessor to know how many times a user has pressed a key.
- We can connect the keypad to the microprocessor pin line, and then use Timer X to detect the key stroke which sends a pulse to pin.



Pseudo code:

Timer initialization
Turn on Timer X

.....
.....

while (the button is pressed)
 Event counting

Read counter register

Step 1: Initialization
Configure the type of Timer / Counter

Step 2: Implementation
Run / Stop the timer,
Read the counter register

Description

Abstract idea of project
(Define the functionality of the system)

Data format / representation

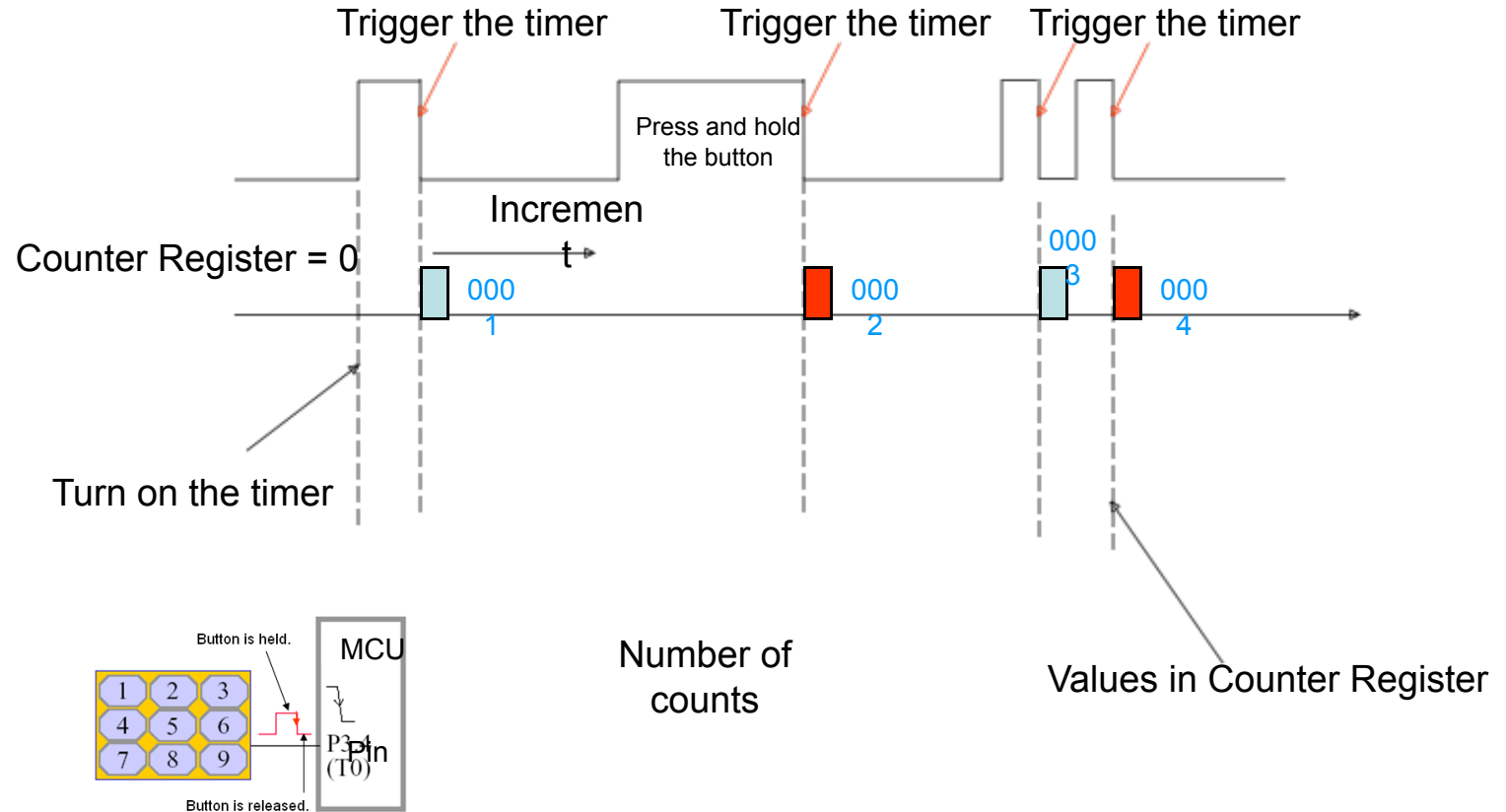
Programming Language

Communication Protocol

Physical connection (Pins assignment)

Hardware devices
(Microcontroller, Peripherals)

Example 1 – Event Counting



Example 1 – Event Counting using STM32

The screenshot displays the STM32CubeIDE interface with the following components:

- Pinout & Configuration** (Left Panel):
 - Search bar with a dropdown arrow.
 - Categories: A-Z.
 - System Core >
 - Analog >
 - Timers >
 - RTC
 - TIM1** (Selected)
 - TIM2
 - TIM3
 - TIM4
 - TIM5
 - TIM6
 - TIM7
 - TIM8
 - Connectivity >
 - Multimedia >
 - Computing >
 - Middleware >
- Clock Configuration** (Top Bar):
 - Additional Software
 - Pinout
- Project Manager** (Top Bar):
 - Pinout view
 - System view
- Tools** (Top Bar):
 - Pinout view
 - System view
- Configuration** (Main Panel):
 - TIM1 Mode and Configuration**
 - Mode: Mode
 - Slave Mode: Disable
 - Trigger Source: TIM1_ED
 - Clock Source: Disable
 - Channel1: Disable
 - Channel2: Disable
 - Channel3: Disable
 - Channel4: Disable
 - Combined Channels: Disable
 - ☐ Activate-Break-Input
 - ☐ Use ETR as Clearing Source
 - Configuration**
 - Reset Configuration
 - Parameter Settings (Selected) | User Constants | NVIC Settings | DMA Settings | GPIO Settings
 - Configure the below parameters:
 - Search (Ctrl+F)
 - Counter Settings
 - Prescaler (PSC - 16 bits value): 0
 - Counter Mode: Up
 - Counter Period (AutoReload Register - 16 bit...): 0
 - Internal Clock Division (CKD): No Division
 - Repetition Counter (RCR - 8 bits value): 0
 - auto-reload preload: Disable
 - Slave Mode Controller: Slave mode disable
- Pinout** (Right Panel):
 - STM32F103VETx LQFP100
 - Pinout view
 - System view
 - Search bar

Example 1 – Event Counting using STM32

External switch

TIM1 Mode and Configuration

Mode

Slave Mode: Disable

Trigger Source: TI1_ED

Clock Source: Disable

Channel1: Disable

Channel2: Disable

Channel3: Disable

Channel4: Disable

Combined Channels: Disable

☐ Activate-Break-Input

☐ Use ETR as Clearing Source

Configuration

Reset Configuration

Parameter Settings | User Constants | NVIC Settings | DMA Settings | GPIO Settings

Configure the below parameters :

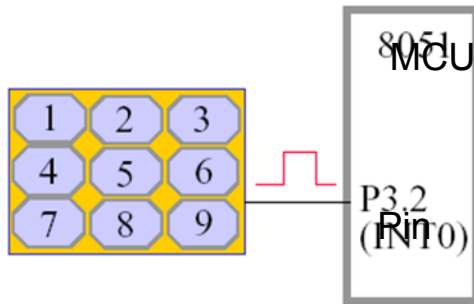
Search (Ctrl+F)

Counter Settings

Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 16 bit...	0
Internal Clock Division (CKD)	No Division
Repetition Counter (RCR - 8 bits value)	0
auto-reload preload	Disable
Slave Mode Controller	Slave mode disable

Example 2 – Timing the Length of Events

- To measure how long (time) a key is being pressed:
- We can connect the keypad to a another pin.
- In this way, the timer X will run when pulse is high (or a key is held down). When pulse is low (or a key is released), the timer X will be stopped.



Pseudo code:

Timer initialization
Turn on Timer X

.....
.....

If the pulse is high, trigger the timer X

If the pulse is low, stop the timer X

Read counter register

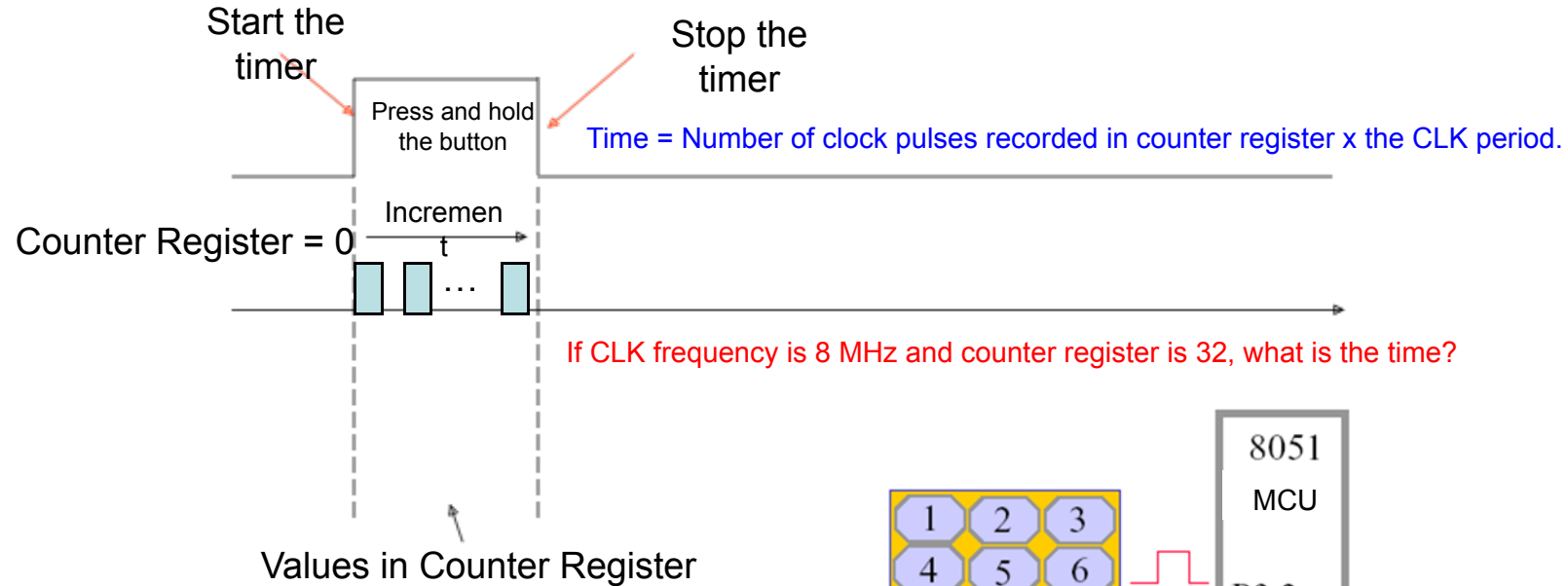
Step 1: Initialization
Configure the type of Timer / Counter

Step 2: Implementation
Run / Stop the timer,
Read the counter register

- From the current counter value and the frequency of the input clock, we can calculate the time elapsed for the event.

Description
Abstract idea of project (Define the functionality of the system)
Data format / representation
Programming Language
Communication Protocol
Physical connection (Pins assignment)
Hardware devices (Microcontroller, Peripherals)

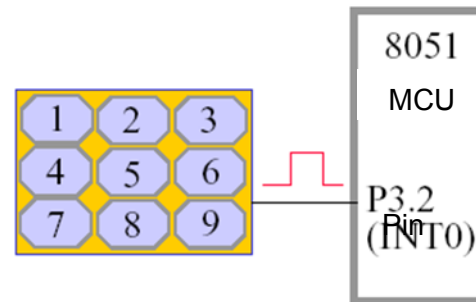
Example 2 – Timing the Length of Events



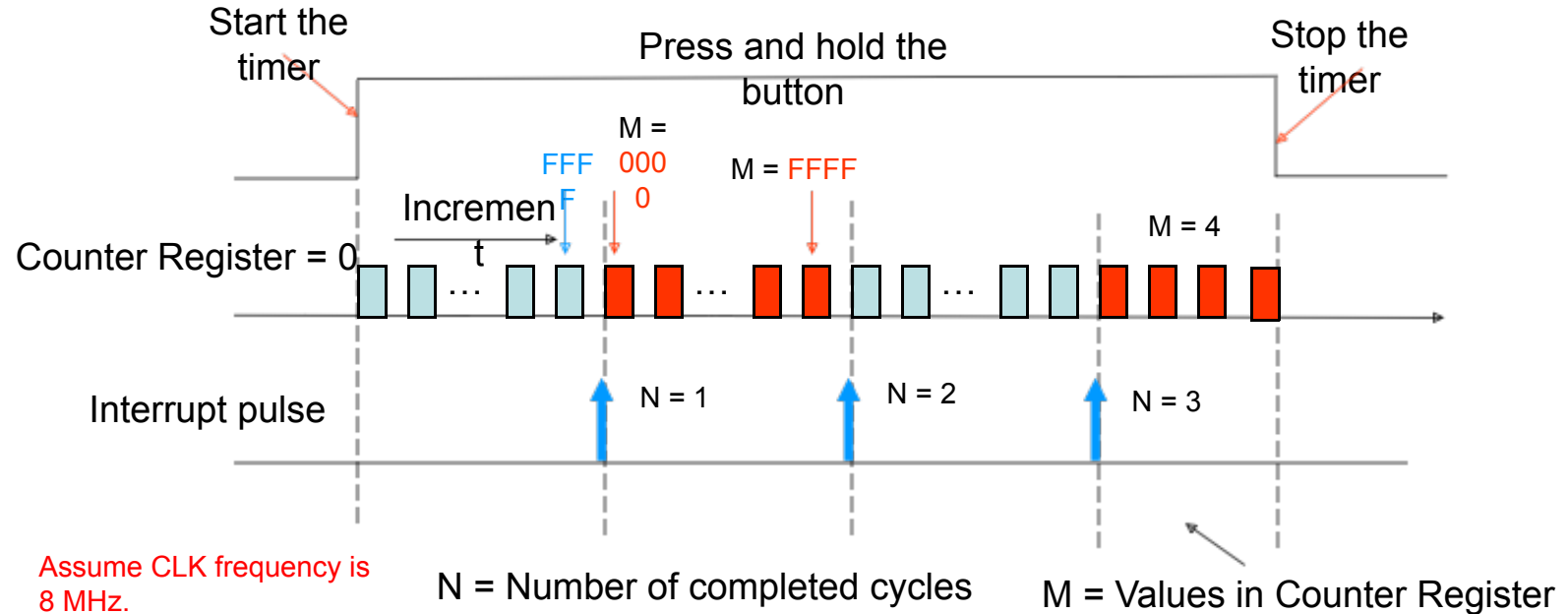
Counter register in STM32 is 16 bits. Max count = $2^{16} = 65,536$.

Maximum time duration possible = $(65,536 \times 1/8) \mu s = 8.192 \text{ ms}$.

Assume that your application needs to time more than 8.192 ms. How will you achieve this?



Example 2 – Timing the Length of Events



Assume CLK frequency is 8 MHz.

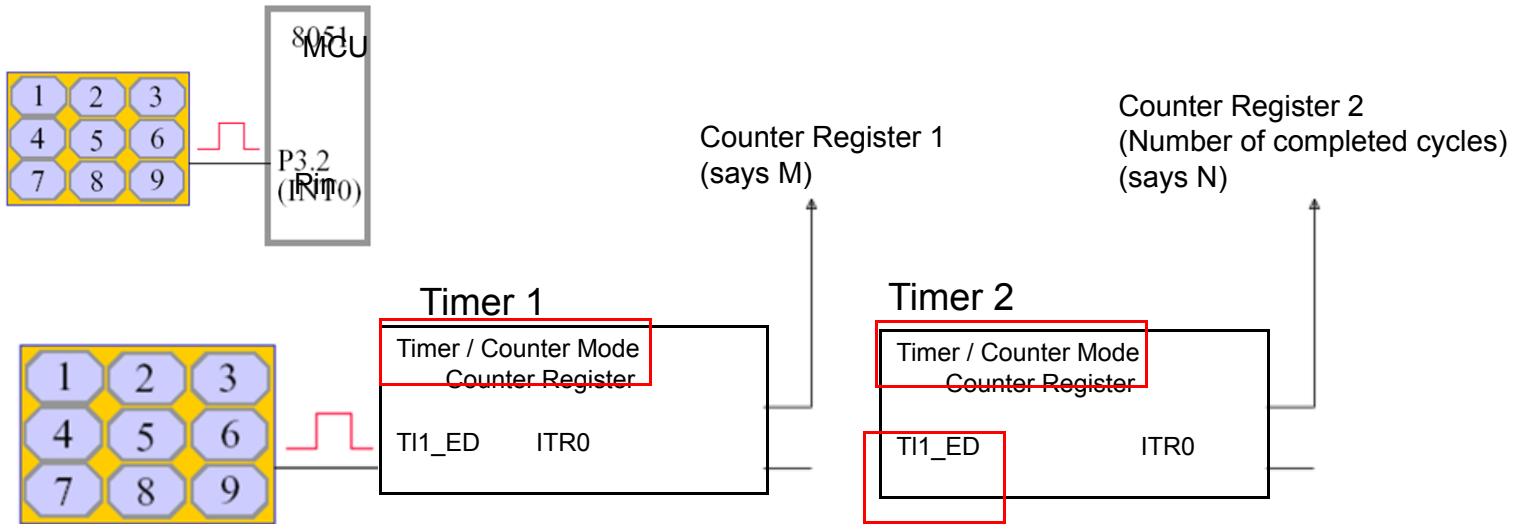
$$\text{Total number of count} = (N \times 216) + M$$

$$\text{Total time} = [(N \times 216) + M] / 8$$

Design Problem: The application engineer tells you that the time needed for an event is at least 1 sec. How will you meet the requirement? Assume clock frequency is 4 MHz.

$$\text{Solution: } N \times 216 \geq \frac{1}{4 \text{ MHz}} \Rightarrow N \geq 61.03$$

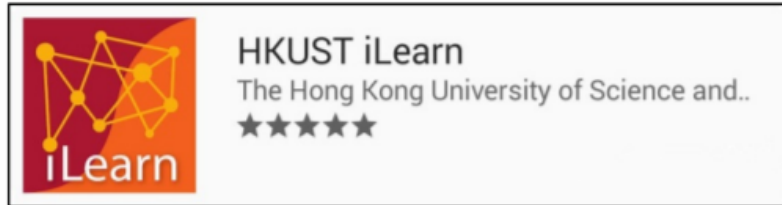
Example 2 – Timing the Length of Events



For every increment in 'N' (which happens when timer count hits FFFF), interrupt pulse will be generated at ITR0 of Timer 1, which triggers the input TI1_ED of Timer 2.

In-class Quiz (Question 1 – 4)

For Android devices, search **HKUST iLearn** at Play Store.



For iOS devices, search **HKUST iLearn** at App Store.



Example 2 – Timing the Length of Events

Timer 1 TIM1 Mode and Configuration

Mode

Slave Mode	Disable
Trigger Source	TI1_ED
Clock Source	Internal Clock
Channel1	Disable
Channel2	Disable
Channel3	Disable
Channel4	Disable
Combined Channels	Disable

☐ Activate-Break-Input
☐ Use ETR as Clearing Source

Configuration

Reset Configuration

Parameter Settings User Constants NVIC Settings DMA Settings GPIO Settings

Configure the below parameters :

Search (Ctrl+F)

Counter Settings

Prescaler (PSC - 16 bits value)	63
Counter Mode	Up
Counter Period (AutoReload Register - 16 bit...	0
Internal Clock Division (CKD)	No Division
Repetition Counter (RCR - 8 bits value)	0
auto-reload preload	Disable
Slave Mode Controller	Slave mode disable

Example 2 – Timing the Length of Events

Timer 1 TIM1 Mode and Configuration

Mode

Slave Mode

Trigger Source

Clock Source

Channel1

Channel2

Channel3

Channel4

Combined Channels

☐ Activate-Break-Input

☐ Use ETR as Clearing Source

Configuration

Reset Configuration

☒ Parameter Settings ☒ User Constants ☒ NVIC Settings ☒ DMA Settings ☒ GPIO Settings

Configure the below parameters :

Search (Ctrl+F)

Repetition Counter (RCR - 8 bits value) 0

auto-reload preload Disable

Slave Mode Controller Slave mode disable

Trigger Output (TRGO) Parameters

Master/Slave Mode (MSM bit) Enable (Trigger delayed for master/slaves simultaneous...)

Trigger Event Selection Update Event

Trigger Filter (4 bits value) 0

Example 2 – Timing the Length of Events

Gated mode: counter Active only when the level of input signal is High.

The screenshot displays the STM32CubeMX configuration interface for Timer 2. The left sidebar shows the project structure with 'Timer 2' selected. The main panel is divided into two sections: 'Mode' and 'Configuration'.

Mode Section:

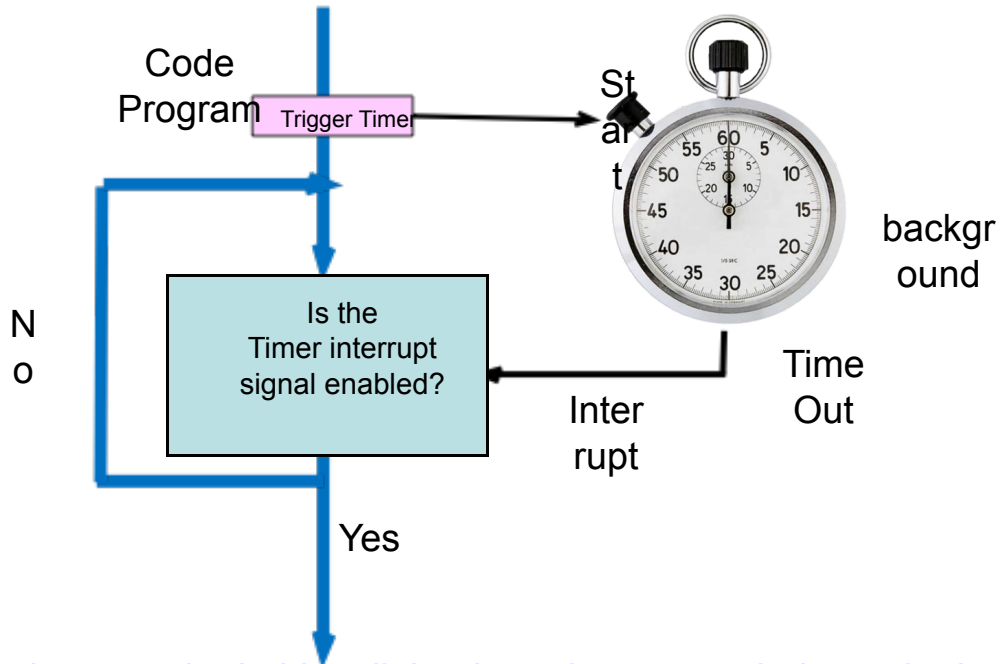
- Slave Mode: Gated Mode
- Trigger Source: ITR0
- Clock Source: Disable
- Channel1: Disable
- Channel2: Disable
- Channel3: Disable
- Channel4: Disable
- Combined Channels: Disable
- ☐ Use ETR as Clearing Source
- ☐ XOR activation

Configuration Section:

- Reset Configuration
- Parameter Settings (checked)
- User Constants (checked)
- NVIC Settings (checked)
- DMA Settings (checked)
- Configure the below parameters :
- Search (Ctrl+F)
- Counter Settings
 - Prescaler (PSC - 16 bits value): 0
 - Counter Mode: Up
 - Counter Period (AutoReload Register - 16 bit...): 0
 - Internal Clock Division (CKD): No Division
 - auto-reload preload: Disable
 - Slave Mode Controller: Gated Mode
- Trigger Output (TRGO) Parameters

Program flow

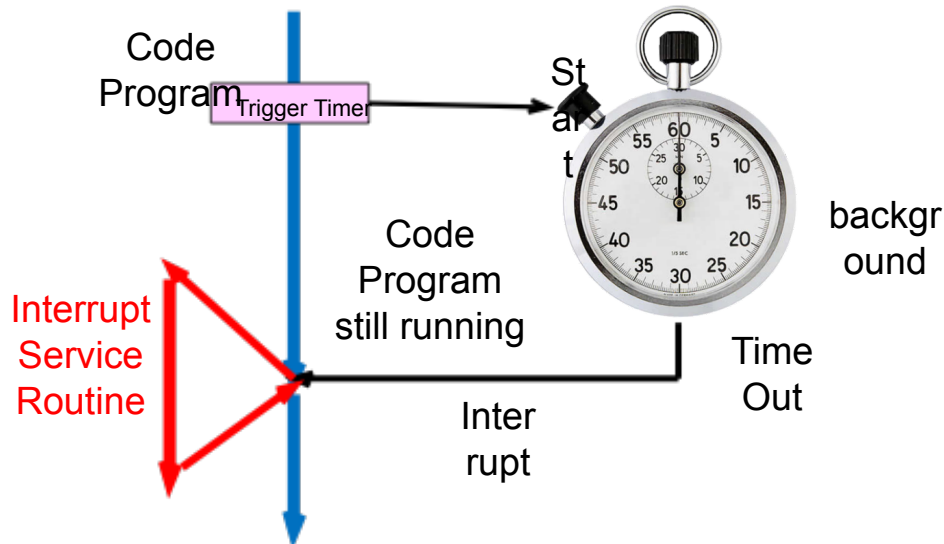
- Timer can be used as a delay function call.



Main program is put under hold until the timer time out and trigger the interrupt, which will enable the main program to resume. Purpose - To introduce a delay to the main program.

Program flow

- Interrupt I/O allows the clock to interrupt the CPU announcing that the device requires attention. This allows CPU to ignore devices unless they request servicing via interrupt



Main program continues to run until the timer time out and triggers the interrupt. Upon receiving the interrupt signal, the main program will stop execution, branch to execute the ISR and return to resume the main program after completing the ISR.

STM32 : Structure of general-purpose timer (TIM2 -TIM5)

- The high-density STM32F103xx performance line devices include up to two advanced control timers, up to four general-purpose timers, two basic timers, two watchdog timers and a SysTick timer.
 - TIM1 / TIM8 – advanced control timers
 - TIM2 / TIM3 / TIM4 / TIM5 – general purpose timers
 - TIM6 / TIM7 – basic timers

Table 4 compares the features of the advanced-control, general-purpose and basic timers.

Table 4. Timer feature comparison

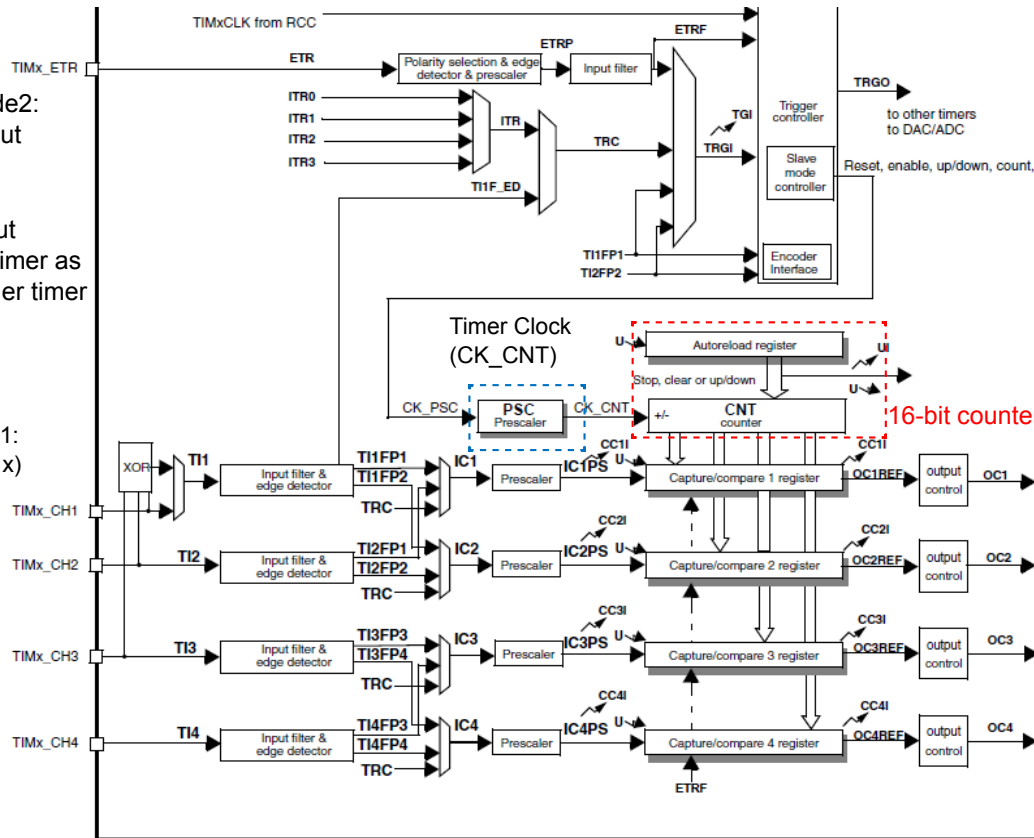
Timer	Counter resolution	Counter type	Prescaler factor	DMA request generation	Capture/compare channels	Complementary outputs
TIM1, TIM8	16-bit	Up, down, up/down	Any integer between 1 and 65536	Yes	4	Yes
TIM2, TIM3, TIM4, TIM5	16-bit	Up, down, up/down	Any integer between 1 and 65536	Yes	4	No
TIM6, TIM7	16-bit	Up	Any integer between 1 and 65536	Yes	0	No




STM32 : Structure of general-purpose timer (TIM2 -TIM5)

External clock mode2:
external trigger input
(ETR)

Internal trigger input
(ITRx): using one timer as
prescaler for another timer

External clock mode1:
external input pin (Tlx)



Notes:	
	Preload registers transferred to active registers on U event according to control bit
	event
	interrupt & DMA output

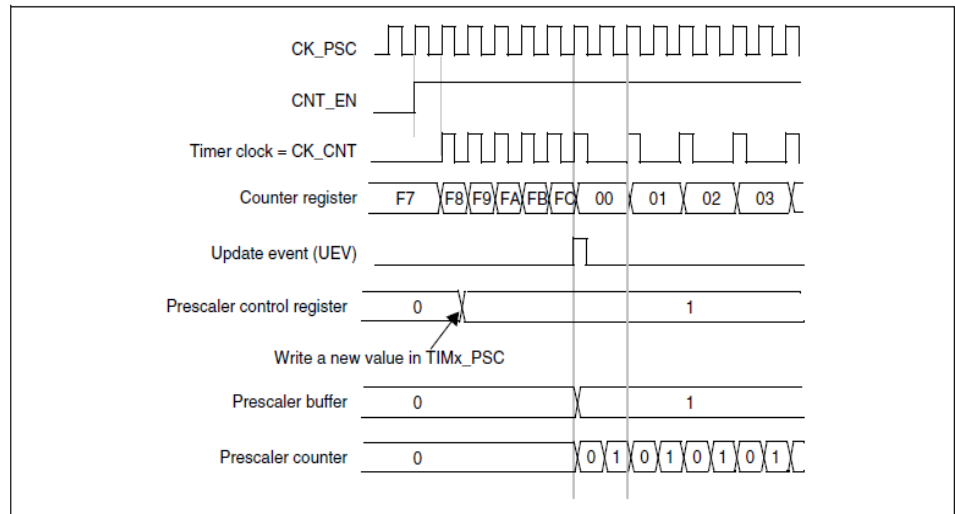
Input Capture
Output Compare
PWM generation
One-pulse mode input

Capture/compare transfers the counter value to the capture register and stores it (eg. To indicate DMA period).

STM32 : Structure of general-purpose timer (TIM2 -TIM5)

Generate the Timer Clock

Figure 101. Counter timing diagram with prescaler division change from 1 to 2



* Upcounting configuration is employed.

STM32 : Structure of general-purpose timer (TIM2 -TIM5)

With auto-reload features, says $TIMx_ARR = 0X36h$

Figure 103. Counter timing diagram, Internal clock divided by 1

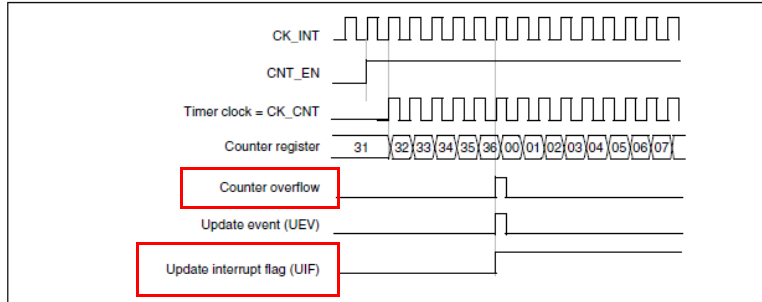


Figure 105. Counter timing diagram, Internal clock divided by 4

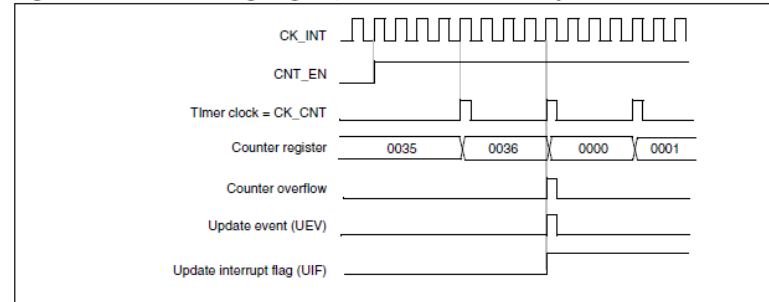


Figure 104. Counter timing diagram, Internal clock divided by 2

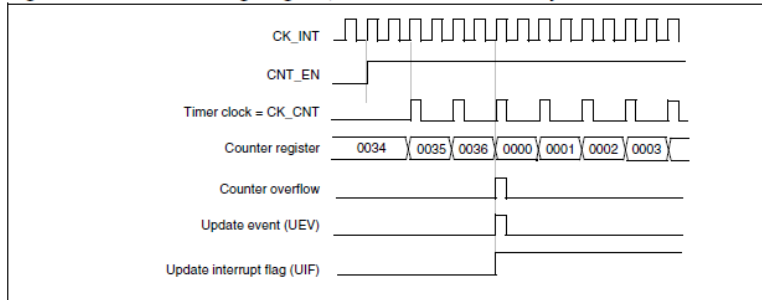
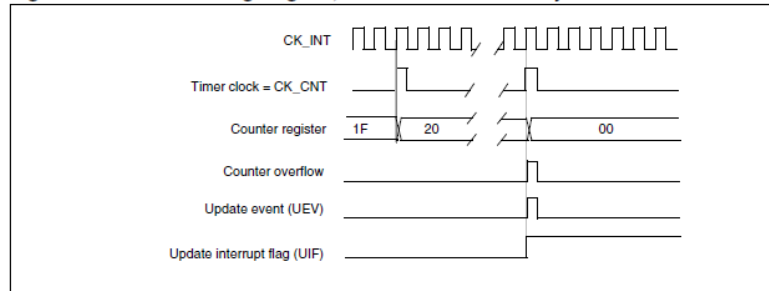


Figure 106. Counter timing diagram, Internal clock divided by N



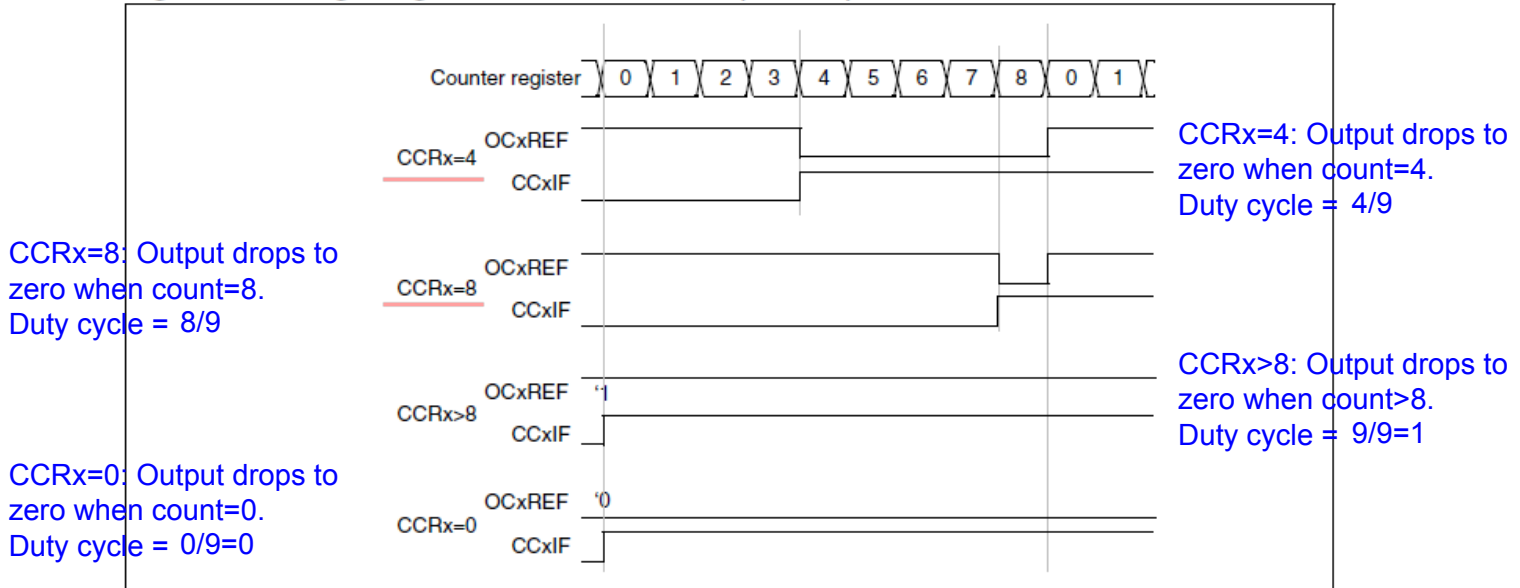
* Upcounting configuration is employed.

STM32 : Structure of general-purpose timer (TIM2 -TIM5)

ARR: Auto Reload Register. When $ARR = 8$, it will produce 0 – 8 counts (total 9 counts).

Figure 130. Edge-aligned PWM waveforms ($ARR=8$)

PWM generation



Resolution of duty cycle = $1/9$.

How can we obtain a duty cycle of 50%?

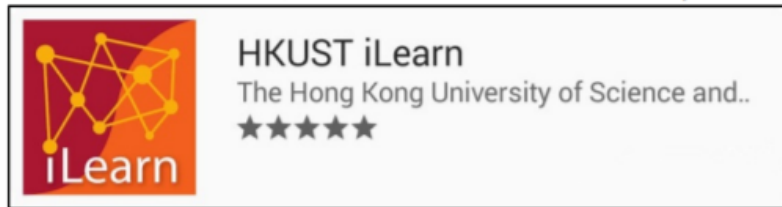
Solution: Set $ARR = 9$.

* Upcounting configuration is employed.

CCR – Capture Compare Register

In-class Quiz (Question 5)

For Android devices, search **HKUST iLearn** at Play Store.



For iOS devices, search **HKUST iLearn** at App Store.



STM32 : Structure of general-purpose timer (TIM2 -TIM5)

If you are not using CubeMX:

- In the initialization of timer, we need to configure

The parameters of input clock rate

TIMx Timebase includes

prescaler register (TIMx_PSC), auto-reload register (TIMx_ARR), etc

The parameters of output waveform

TIMx Output Compare, TIMx_CCRx Register

- For the implementation stage, we just need to **enable the timer / counter pin**

The result will be stored in the Counter Register (TIMx_CNT), Output Compare Register (OCxREF), etc

Can you configure these settings in CubeMX?

Real-world Examples

Bottle counting (Mineral water bottling plant)



To count the number of bottles:
Optical sensors + Counter

A bit more challenging problem: Can you propose a system that counts and displays the number of customers in the 7-11 store at a given instance of time?

Clue: You have to increase the count (when customer enters and decrease the count (when customer leaves).

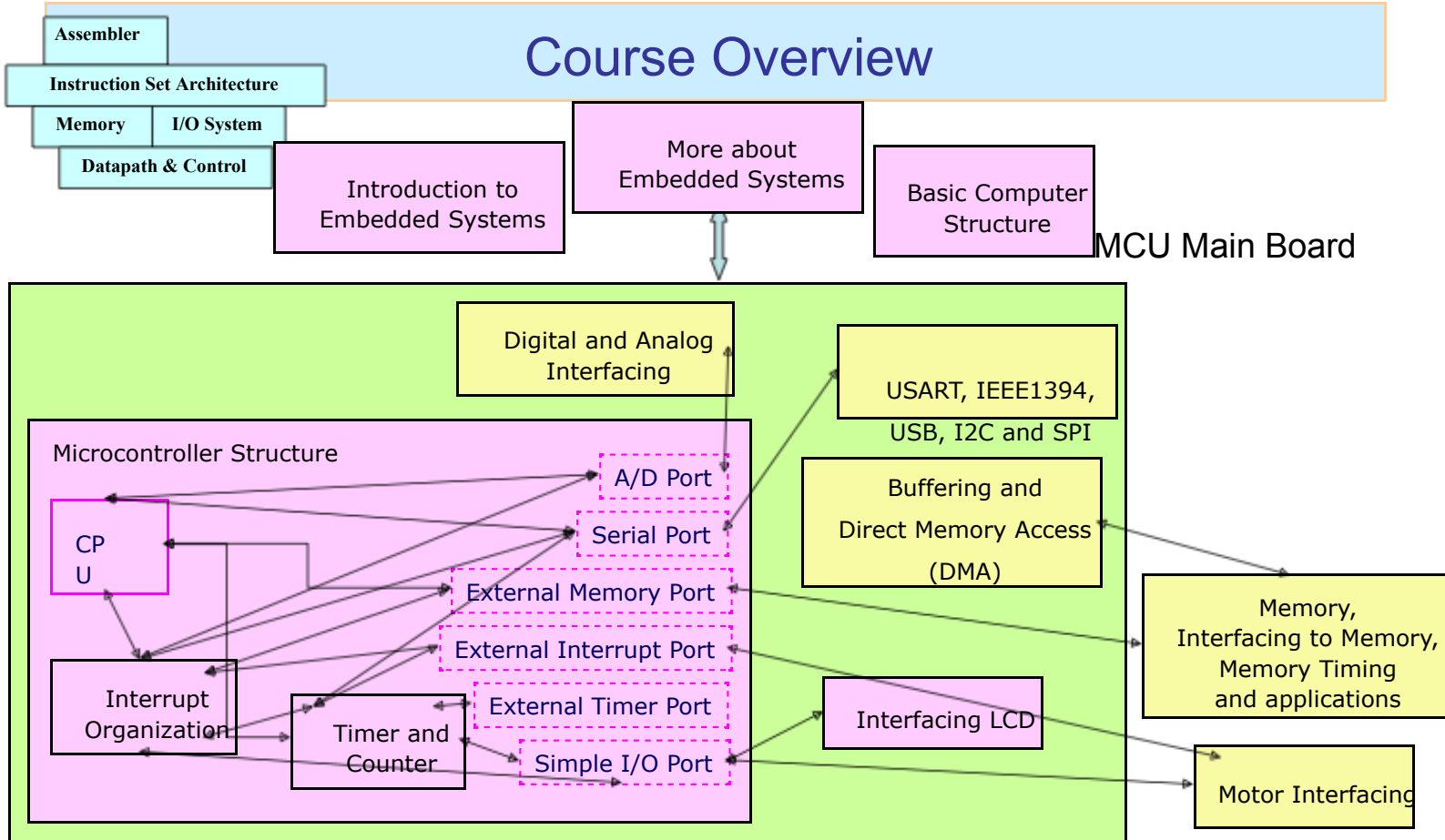


Different problems, Similar solutions: Can you propose a system that counts and displays the number of vacant seats in the upper deck of KMB double decker bus?

Reflection (Self-evaluation)

- Do you ...
 - List some applications for timer / counter operation ?
 - State the important registers in the timer / counter operation?
 - Write the sub-routines for event counting or timing the length of event?
 - Describe the counter timing diagram in the count-down operation with different parameters (Clock frequency, up/down; auto-reload values)?

Course Overview



In this course, STM32 is used as a driving vehicle for delivering the concepts.

To be covered	In progress	Done
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